

Lorem ipsum Lorem ipsum Lorem ipsum Lorem ipsum

Holger KUMKE and Jukka KRISP

Department of Cartography · Technische Universität München · Arcisstraße 21 · 80333 Munich

Tel.: +49 (0)89 123 456 78 · E-Mail: Lorem.Ipsum@tum.de

Keywords: Lorem, ipsum, dolor, sit, amet

Summary: Lorem ipsum dolor sit amet, consetetur sadipscing elitr, sed diam nonumy eirmod tempor invidunt ut labore et dolore magna aliquyam erat, sed diam voluptua. At vero eos et accusam et justo duo dolores et ea rebum. Stet clita kasd gubergren, no sea takimata sanctus est Lorem ipsum dolor sit amet. Lorem ipsum dolor sit amet, consetetur sadipscing elitr, sed diam nonumy eirmod tempor invidunt ut labore et dolore magna aliquyam erat, sed diam voluptua. At vero eos et accusam et justo duo dolores et ea rebum. Stet clita kasd gubergren, no sea takimata sanctus est Lorem ipsum dolor sit amet.

1 Introduction

Lorem ipsum dolor sit amet, consetetur sadipscing elitr, sed diam nonumy eirmod tempor invidunt ut labore et dolore magna aliquyam erat, sed diam voluptua. At vero eos et accusam et justo duo dolores et ea rebum. Stet clita kasd gubergren, no sea takimata sanctus est Lorem ipsum dolor sit amet. Lorem ipsum dolor sit amet, consetetur sadipscing elitr, sed diam nonumy eirmod tempor invidunt ut labore et dolore magna aliquyam erat, sed diam voluptua. At vero eos et accusam et justo duo dolores et ea rebum. Stet clita kasd gubergren, no sea takimata sanctus est Lorem ipsum dolor sit amet.

$$x' = Hx. \quad (1)$$

Lorem ipsum dolor sit amet, consetetur sadipscing elitr, sed diam nonumy eirmod tempor invidunt ut labore et dolore magna aliquyam erat, sed diam voluptua. At vero eos et accusam et justo duo dolores et ea rebum. Stet clita kasd gubergren, no sea takimata sanctus est Lorem ipsum dolor sit amet. Lorem ipsum dolor sit amet, consetetur sadipscing elitr, sed diam nonumy eirmod tempor invidunt ut labore et dolore magna aliquyam erat, sed diam voluptua. At vero eos et accusam et justo duo dolores et ea rebum. Stet clita kasd gubergren, no sea takimata sanctus est Lorem ipsum dolor sit amet.

1.1 3D Reconstruction

Lorem ipsum dolor sit amet, consetetur sadipscing elitr, sed diam nonumy eirmod tempor invidunt ut labore et dolore magna aliquyam erat, sed diam voluptua.



Fig. 1: Lorem ipsum dolor sit amet

Acknowledgement

Lorem ipsum dolor sit amet, consetetur sadipscing elitr, sed diam nonumy eirmod tempor invidunt ut labore et dolore magna aliquyam erat, sed diam voluptua. At vero eos et accusam et justo duo dolores et ea rebum. Stet clita kasd gubergren, no sea takimata sanctus est Lorem ipsum dolor sit amet.

References

- BAILLARD, C. & ZISSERMAN, A., 1999: Automatic Reconstruction of Piecewise Planar Models from Multiple Views. – Computer Vision and Pattern Recognition, Volume II: 559–565.
- BÖHM, J., 2004: Multi Image Fusion for Occlusion-Free Façade Texturing. – The International Archives of the Photogrammetry, Remote Sensing and Spatial Information Sciences, Volume 35 (B5): 867–872.
- CHUM, O., MATAS, J. & KITTLER, J., 2003: Locally Optimized RANSAC. – Pattern Recognition – DAGM 2003, Springer-Verlag, Berlin, Germany, 249–256.
- DEBEVEC, P., TAYLOR, C. & MALIK, J., 1996: Modeling and Rendering Architecture from Photographs: A Hybrid Geometry- and Image-Based Approach. – Technical Report CSD-96-893, Computer Science Division, University of California at Berkeley, Berkeley, USA.
- FÖRSTNER, W. & GÜLCH, E., 1987: A Fast Operator for Detection and Precise Location of Distinct Points, Corners and Centres of Circular Features. – ISPRS Intercommission Conference on Fast Processing of Photogrammetric Data, Interlaken, Switzerland, 281–305.
- HARTLEY, R. & ZISSERMAN, A., 2003: Multiple View Geometry in Computer Vision. – Second Edition, Cambridge University Press, Cambridge, UK.
- LHULLIER, M. & QUAN, L., 2005: A Qasi-Dense Approach to Surface Reconstruction from Uncalibrated Images. – IEEE Transactions on Pattern Analysis and Machine Intelligence 27 (3): 418–433.
- MIKHAIL, E., BETHEL, J. & MCGLONE, J., 2001: Introduction to Modern Photogrammetry. – John Wiley & Sons, Inc, New York, USA.
- POLLEFEYS, M., VAN GOOL, L., VERGAUWEN, M., VERBIEST, F., CORNELIS, K. & TOPS, J., 2004: Visual Modeling with a Hand-Held Camera, International Journal of Computer Vision 59 (3): 207–232.
- SCHNABEL, R., WAHL, R. & KLEIN, R., 2006: Shape Detection in Point Clouds, Technical Report CG-2006-2, Universität Bonn.